

Semi-Supervised Learning via Triplet Network Based Active Learning

Divyanshu Sundriyal¹, Soumyadeep Ghosh¹, Mayank Vatsa², Richa Singh²

¹IIT-Delhi, ²IIT Jodhpur

{divyanshu18096, soumyadeepg}@iiitd.ac.in, {mvatsa, richa}@iitj.ac.in

Abstract

In recent years, deep learning models have pushed state-of-the-art accuracies for several machine learning tasks. However, such models require a large amount of (supervised) data for training. While unlabelled data is available in abundance, manually labeling them is very costly. Active learning techniques help in utilizing unlabelled data which may result in an improved classification model. In this research, we present an active learning algorithm which can help in increasing performance of deep learning models by using large amount of unlabelled data. A novel active learning algorithm, Triplet AL is proposed which uses a triplet network to select samples from an unlabelled data set. Previous active learning methods rely on classification model's final prediction scores as a measure of confidence for an unlabelled sample. We propose a more reliable confidence measure, termed as Top-Two-Margin which is given by the Triplet Network. The proposed algorithm outperforms other active learning approaches which are used to compare in this research.

Introduction

There are several applications in the real world with limited labelled samples that are inadequate to train a good classification model. However, these applications can be benefitted with the availability of huge amount of unlabelled images. In such cases, semi-supervised learning techniques are beneficial as they utilize a small labelled set of data along with a large unlabelled set which can be used to increase model performance. This research presents a novel active learning algorithm that can be used to select samples from the unlabelled set in iterative manner and pseudo label the selected samples such that these pseudo labelled samples when added to current initial labelled set would allow us to train an improved supervised classification model.

Proposed Algorithm

Conventional active learning methods consist of a classification model M_1 whose purpose is to learn a function $g_\theta : \mathbb{R}^Z \rightarrow \mathbb{R}^K$, where Z is the dimensionality of input manifold and K is the number of classes. In the proposed **Triplet AL** method, along with classification model

Copyright © 2021, Association for the Advancement of Artificial Intelligence (www.aaai.org). All rights reserved.

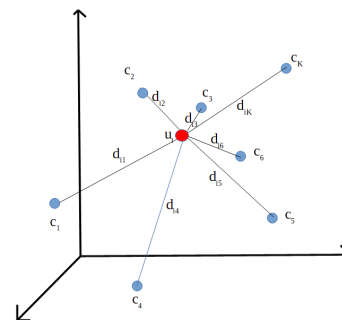


Figure 1: Distance of unlabelled data point u_i to K class centers. Embedding space of size N is illustrated using an embedding space of size 3 for representational purposes.

M_1 , a triplet model M_2 is also used. Purpose of model M_2 is to learn a function $f_\phi : \mathbb{R}^Z \rightarrow \mathbb{R}^N$ using triplet loss (Schroff, Kalenichenko, and Philbin 2015), where Z is the dimensionality of the input manifold and N is the size of embedding space. The proposed algorithm consists of the following steps:

- Train classification model M_1 and embedding model M_2 using initial labelled set L . Class centers $C_1, C_2, C_3 \dots C_K$ are computed in the embedding space. To find the center of a class, embeddings of all samples belonging to that class are computed and mean of the embeddings are obtained.
- For each unlabelled sample p_i , we convert it to its embedding e_i using embedding model M_2 . As shown in Figure 1, distance to all the K centers $[d_{i1}, d_{i2}, d_{i3}, \dots, d_{ik}]$ in the embedding space are obtained. These distances are sorted in ascending order $[D_{i1}, D_{i2}, D_{i3}, \dots, D_{iK}]$ where, distance D_{i1} is the distance of unlabelled sample p_i from its nearest class center and distance D_{i2} is the distance of unlabelled sample p_i from its second nearest class center and so on.
- We propose **Top-Two-Margin** metric as a difference between distance from nearest center and distance from second nearest center. Top-Two-Margin of an unlabelled sample p_i is calculated as, $Top - Two - Margin_i = D_{i2} - D_{i1}$.

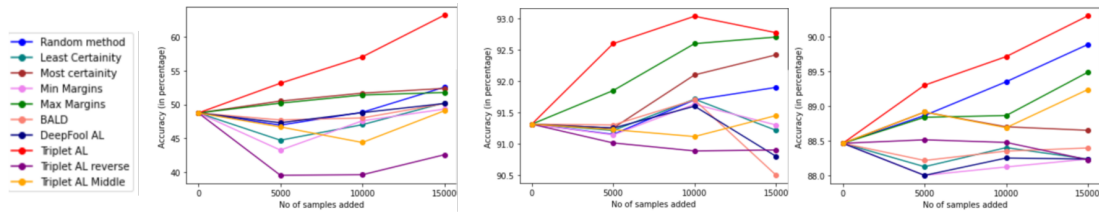


Figure 2: Results on the STL-10 Dataset showing changes in accuracy of model M_1 when samples are added from unlabelled dataset for 3 different architectures namely, M_1 - LeNet-5, ResNet-152 and DenseNet-121.

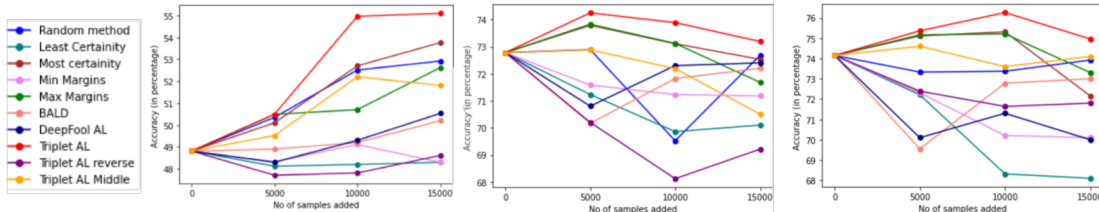


Figure 3: Results on the CIFAR-10 Dataset showing changes in the accuracy of model M_1 when samples are added from unlabelled dataset for 3 different architectures of M_1 - LeNet-5, ResNet-152 and DenseNet-121.

- Top-Two-Margin indicates confidence of Model M_2 on the class of unlabelled sample p_i . If Top-Two-Margin is large, then model M_2 is sure that the sample belongs to the class of its nearest class center. If Top-Two-Margin has a lower value, then model M_2 is very less certain that it belongs to class of its nearest class center. In each iteration of active learning, we select S samples whose Top-Two-Margin is largest i.e. model M_2 is most confident about their class because model M_2 is used as an Oracle.
- For pseudo labelling a selected sample s_i , we convert it to its embedding e_i using M_2 . We calculate the distance of e_i to all class centers and assign a class C to the sample s_i whose center is closest to the sample in embedding space. The pseudo labelled points are then added to the labelled set and are removed from the unlabelled set (so that they are not chosen again). Models M_1 and M_2 are retrained using new labelled set.

Results

To evaluate the proposed algorithm, we have used the STL-10 (Coates, Ng, and Lee 2011) and CIFAR-10 datasets (Krizhevsky and Hinton 2009). For STL-10 dataset, we have 5,000 initial labelled samples and 100,000 unlabelled samples. For CIFAR-10 dataset, we have partitioned the training set of 50,000 samples into 5000 labelled and 45,000 unlabelled samples. To demonstrate architectural neutrality, we have used 3 different architectures for classification model M_1 in our experiments: LeNet-5, ResNet-152 and DenseNet-121. We have compared proposed Triplet AL algorithm with other active learning methods such as Random sampling, Least Certainty, Most Certainty, Minimum margin, Maximum margin and two recent active learning algorithms BALD (Gal, Islam, and Ghahramani 2017) and Deep Fool active learning (Ducoffe and Precioso 2018). We have performed three active learning iterations and in each itera-

tion 5,000 samples are selected from the unlabelled set.

The proposed Triplet AL method outperformed other active learning approaches used in this work. Figures 2 and 3 show that increase in accuracy is higher when samples are selected from unlabelled dataset using the proposed algorithm. For the STL-10 dataset, the proposed Triplet AL method is able to increase accuracy of classification model M_1 by 14.55%, 1.72% and 1.84% when classification model used is LeNet-5, ResNet-152, and DenseNet-121, respectively. For the CIFAR-10 dataset, Triplet AL is able to increase accuracy of M_1 by 6.29%, 1.47% and 2.11% when LeNet-5, ResNet-152, and DenseNet-121, respectively are used.

Conclusion and Future Work

This research shows that using an unlabelled set, the proposed Triplet AL algorithm is able to improve the performance of a classification model on the unseen test data. The proposed algorithm outperforms other popular active learning algorithms. In the future, we plan to extend the proposed approach by incorporating a multi task learning model.

References

- Coates, A.; Ng, A.; and Lee, H. 2011. An Analysis of Single-Layer Networks in Unsupervised Feature Learning. In *AISTATS*.
- Ducoffe, M.; and Precioso, F. 2018. Adversarial Active Learning for Deep Networks: A Margin Based Approach. *arXiv preprint arXiv:1802.09841*.
- Gal, Y.; Islam, R.; and Ghahramani, Z. 2017. Deep Bayesian Active Learning with Image Data. In *ICML*, 1183–1192.
- Krizhevsky, A.; and Hinton, G. 2009. Learning multiple layers of features from tiny images. Technical report, University of Toronto.
- Schroff, F.; Kalenichenko, D.; and Philbin, J. 2015. Facenet: A Unified Embedding for Face Recognition and Clustering. In *IEEE CVPR*, 815–823.